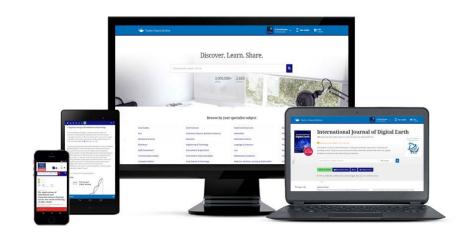




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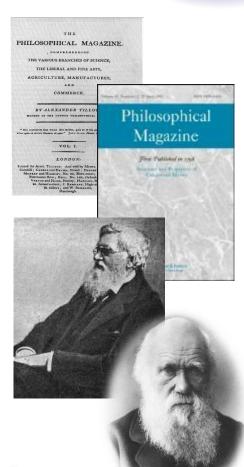












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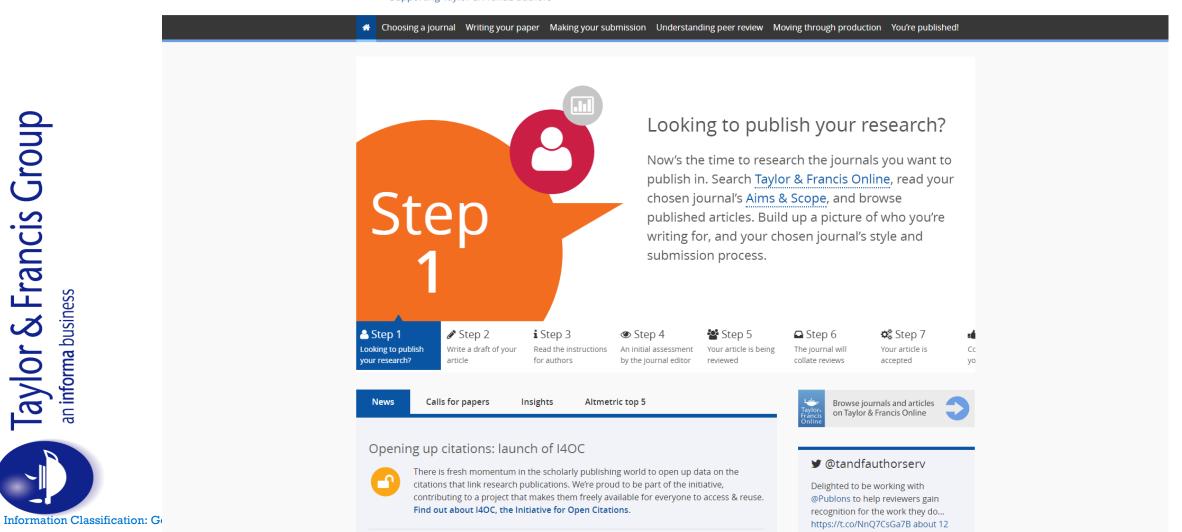
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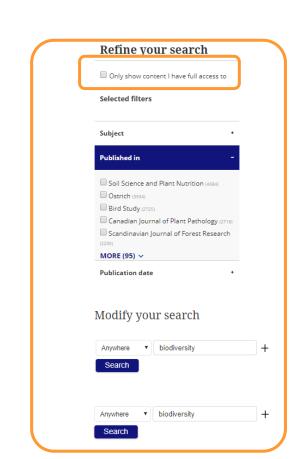


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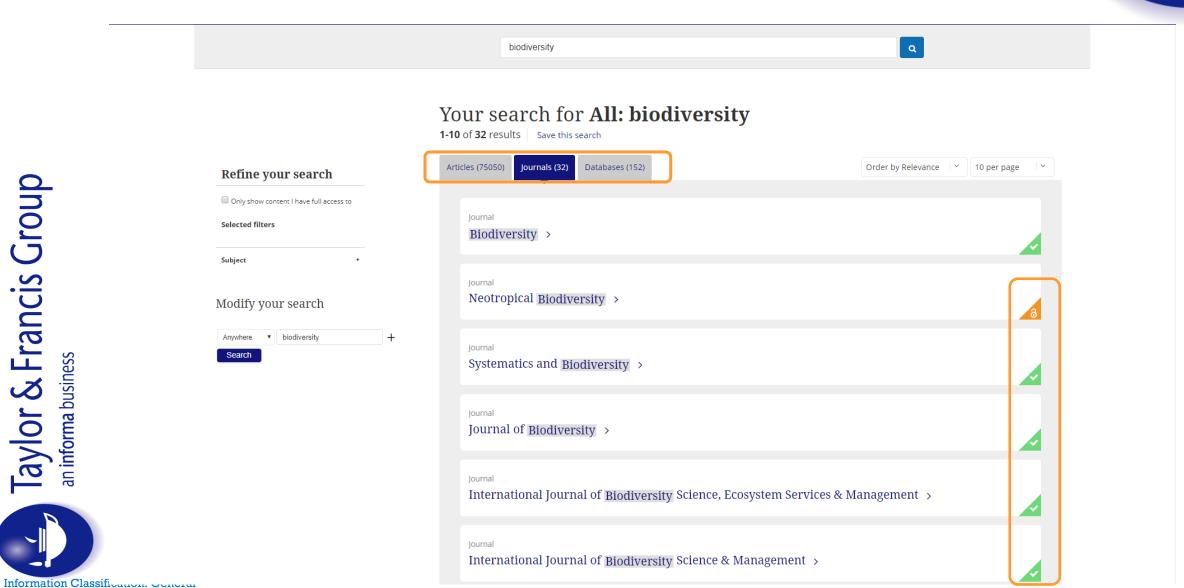
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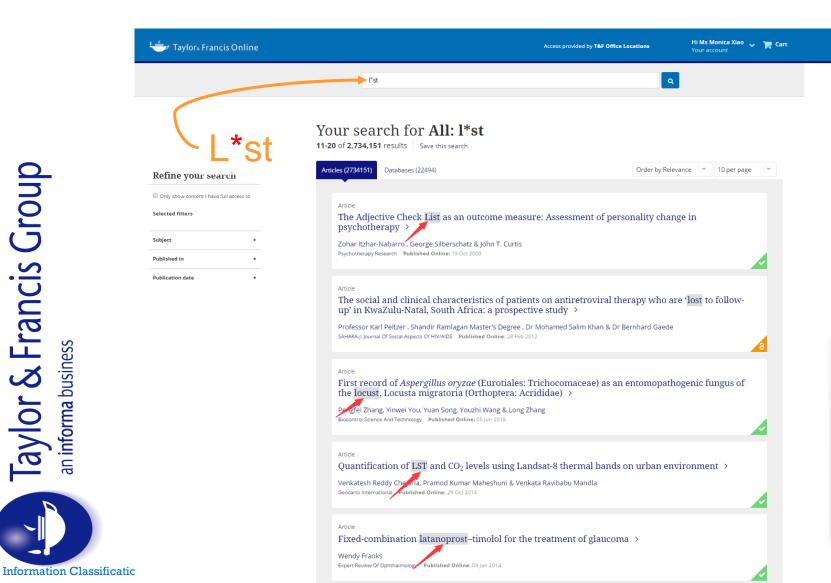
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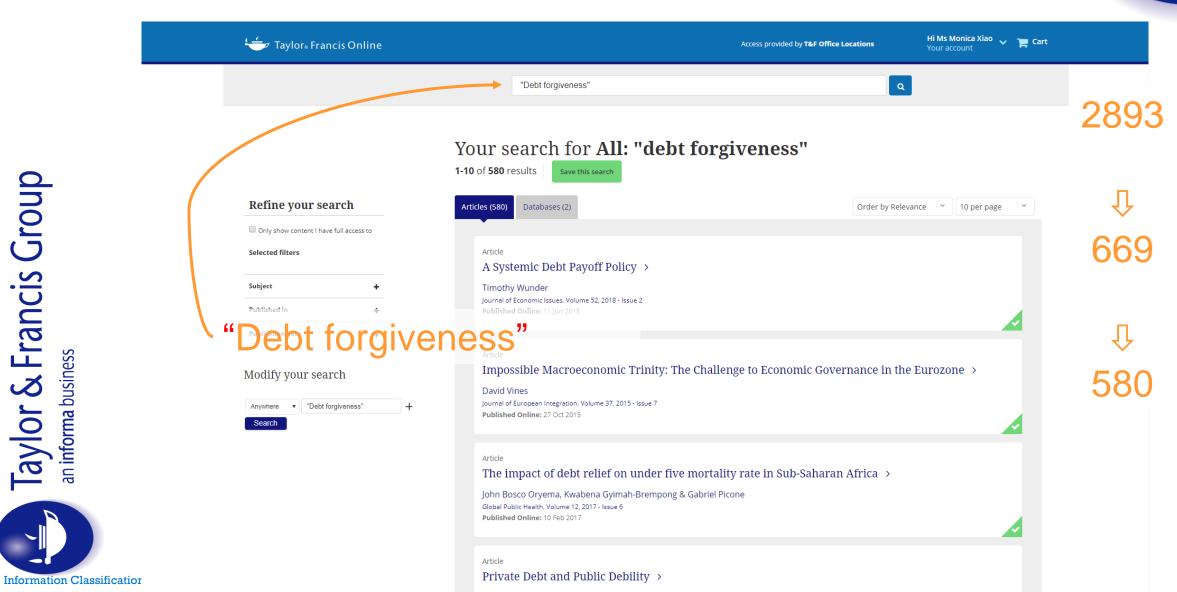
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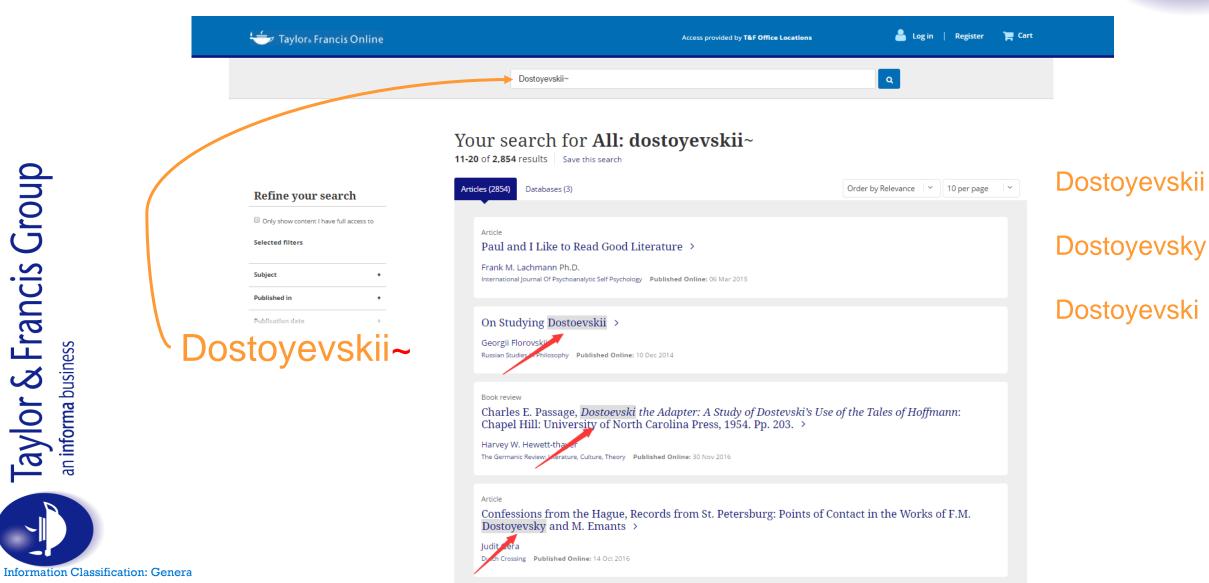




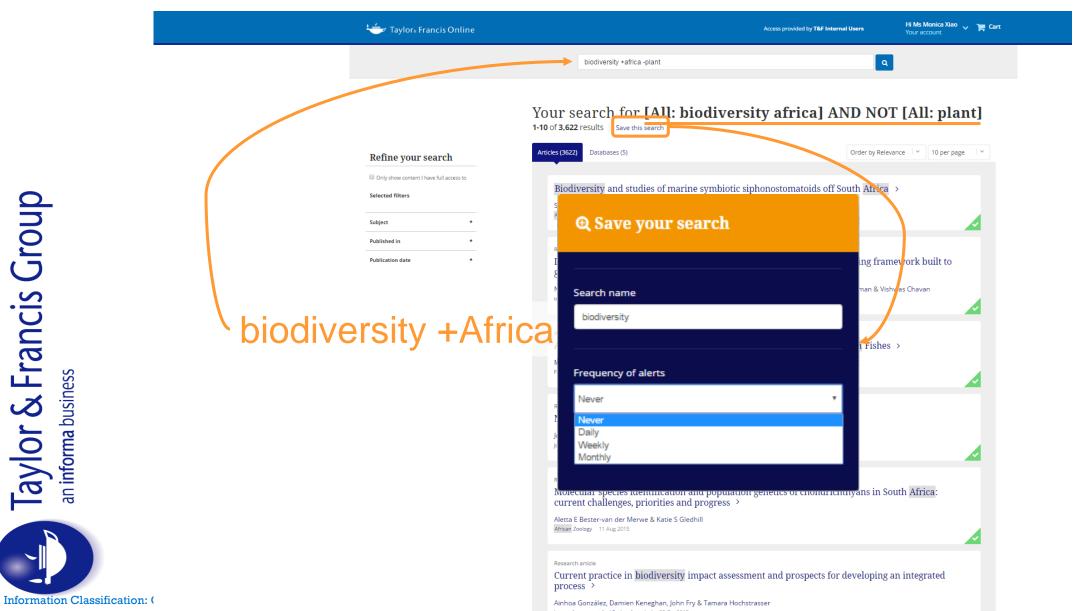
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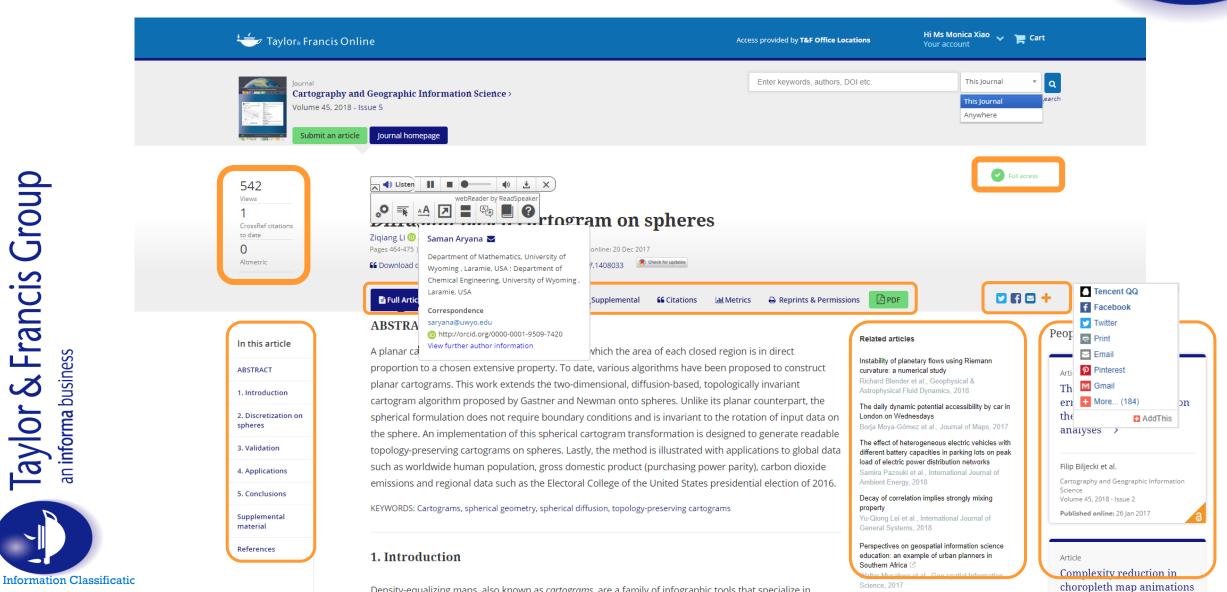




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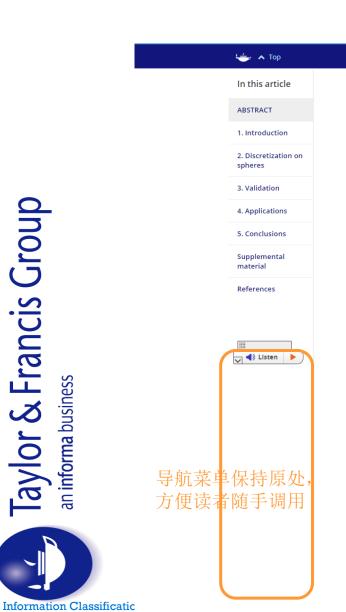
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A planar cartogram is a two-dimensional map, on which the area of each closed region is in direct proportion to a chosen extensive property. To date, various algorithms have been proposed to construct planar cartograms. This work extends the two-dimensional, diffusion-based, topologically invariant cartogram algorithm proposed by Gastner and Newman onto spheres. Unlike its planar counterpart, the spherical formulation does not require boundary conditions and is invariant to the rotation of input data on the sphere. An implementation of this spherical cartogram transformation is designed to generate readable topology-preserving cartograms on spheres. Lastly, the method is illustrated with applications to global data such as worldwide human population, gross domestic product (purchasing power parity), carbon dioxide emissions and regional data such as the Electoral College of the United States presidential election of 2016.

KEYWORDS: Cartograms, spherical geometry, spherical diffusion, topology-preserving cartograms

References

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#### 1. Introduction

Full Article

Density-equalizing maps, also known as cartograms, are a family of infographic tools that specialize in creating maps, on which the areas of nations are linearly proportional to their enclosed extensive property. From the earliest hand-drawn cartograms that date back as far as 1868 (Funkhouser, #2 1937, pp. 355-356) and 1934 (Raisz, 🗐 1934), to the more recent computer-generated cartograms (FiveThirtyEight, 🗐 2016), cartographers have been on the pursuit of the most ideal infographic tool (Alam, Kobourov, & Veeramoni, 2015). Popular applications of the cartogram include population demographics (House & Kocmoud, ┛ 1998), election maps (FiveThirtyEight, ┛ 2016; Gastner & Newman, 🗗 2004), and frequency analysis of events (Gastner & Newman, 🗐 2004). Regardless of their internal details, central to all cartograms is the step to rescale all or part of an ordinary map according to a chosen geospatial-dependent statistic such that this statistic becomes homogenized.

A multitude of algorithms has been designed to create cartograms of varying complexity, accuracy, and purpose (Nusrat & Kobourov, 2016). To meet their specific goals, cartographers have consulted mathematical models in physics, e.g. springs (House & Kocmoud, 🗐 1998) and diffusion (Gastner & Newman, 2004), or have created arbitrary mechanisms that are still mathematically valid (Kämper, Kobourov, & Nöllenburg, 🗗 2013). Some cartographers, e.g. Dougenik, Chrisman, and Niemeyer (🗗 1985), prefer to maintain correct topology at the expense of severe distortion; in the more extreme case, the relative positions of two territories may not be preserved. Cartographers working with discrete quantities,

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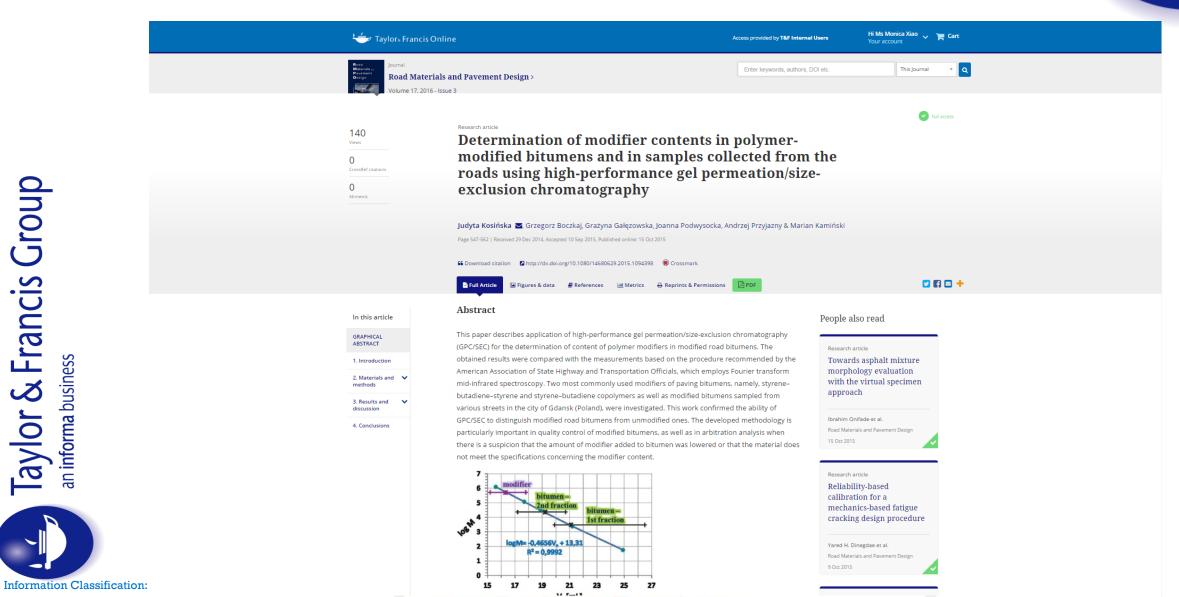
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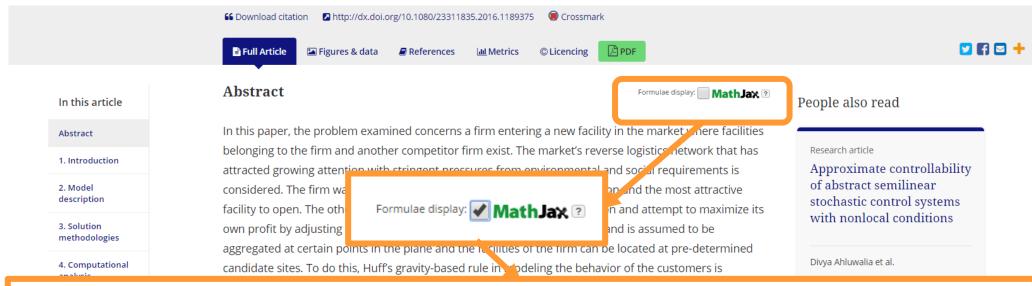
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Now, we can formulate the following bi-level MINLP model P as follows:

(1)

$$P: \max \sum_{j=1}^{n_{1}} h_{j} \frac{\sum_{l \in E} \frac{g_{l}^{f} + g_{l}^{h}}{d_{lj}^{2}} + \sum_{i=1}^{m} \frac{A_{i}}{d_{ij}^{2}}}{\sum_{l \in E} \frac{g_{l}^{f} + g_{l}^{h}}{d_{lj}^{2}} + \sum_{i=1}^{m} \frac{A_{i}}{d_{ij}^{2}} + \sum_{k=1}^{s} \frac{A_{k}}{d_{kj}^{2}}} + \sum_{j=n_{1}+1}^{n} h_{j} \frac{\sum_{l \in E} \frac{g_{l}^{h} + g_{l}^{r}}{d_{lj}^{2}} + \sum_{i=1}^{m} \frac{A_{i}}{d_{ij}^{2}}}{\sum_{l \in E} \frac{g_{l}^{h} + g_{l}^{r}}{d_{lj}^{2}} + \sum_{i=1}^{m} \frac{A_{i}}{d_{ij}^{2}}} + \sum_{k=1}^{s} \frac{A_{k}}{d_{kj}^{2}}} - \sum_{l \in E} (g_{l}^{f} + g_{l}^{h} + g_{l}^{r}) c_{l}$$

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#### ABSTRACT

A planar cartogram is a two-dimensional map, on which the area of each closed region is in direct proportion to a chosen extensive property. To date, various algorithms have been proposed to construct planar cartograms. This work extends the two-dimensional, diffusion-based, topologically invariant cartogram algorithm proposed by Gastner and Newman onto spheres. Unlike its planar counterpart, the spherical formulation does not require boundary conditions and is invariant to the rotation of input data on the sphere. An implementation of this spherical cartogram transformation is designed to generate readable topology-preserving cartograms on spheres. Lastly, the method is illustrated with applications to global data such as worldwide human population, gross domestic product (purchasing power parity), carbon dioxide emissions and regional data such as the Electoral College of the United States presidential election of 2016.

KEYWORDS: Cartograms, spherical geometry, spherical diffusion, topology-preserving cartograms

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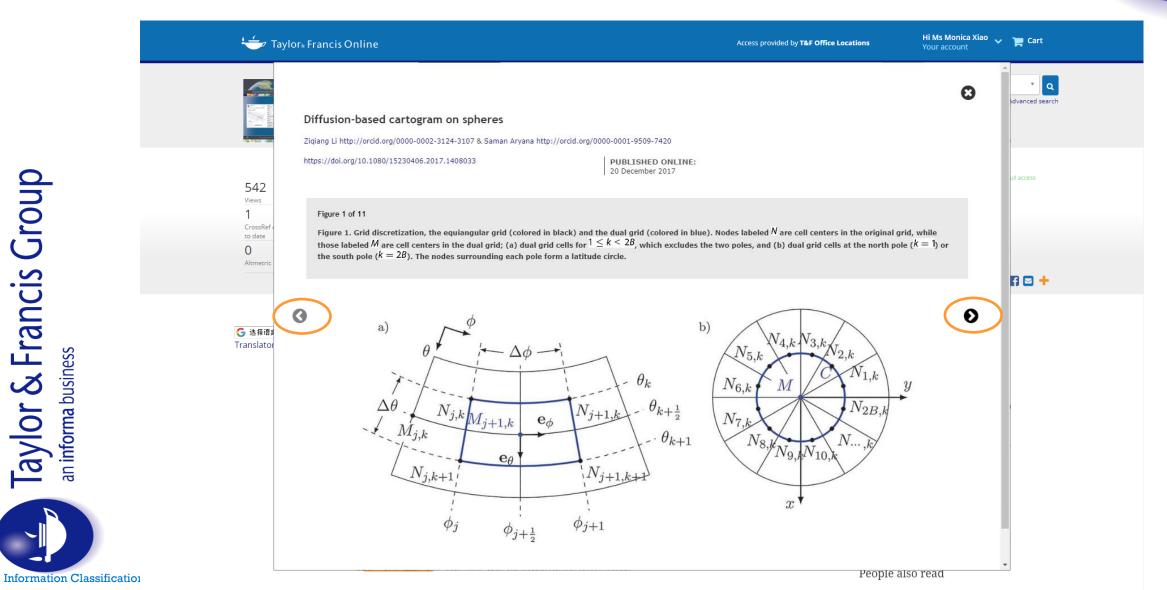
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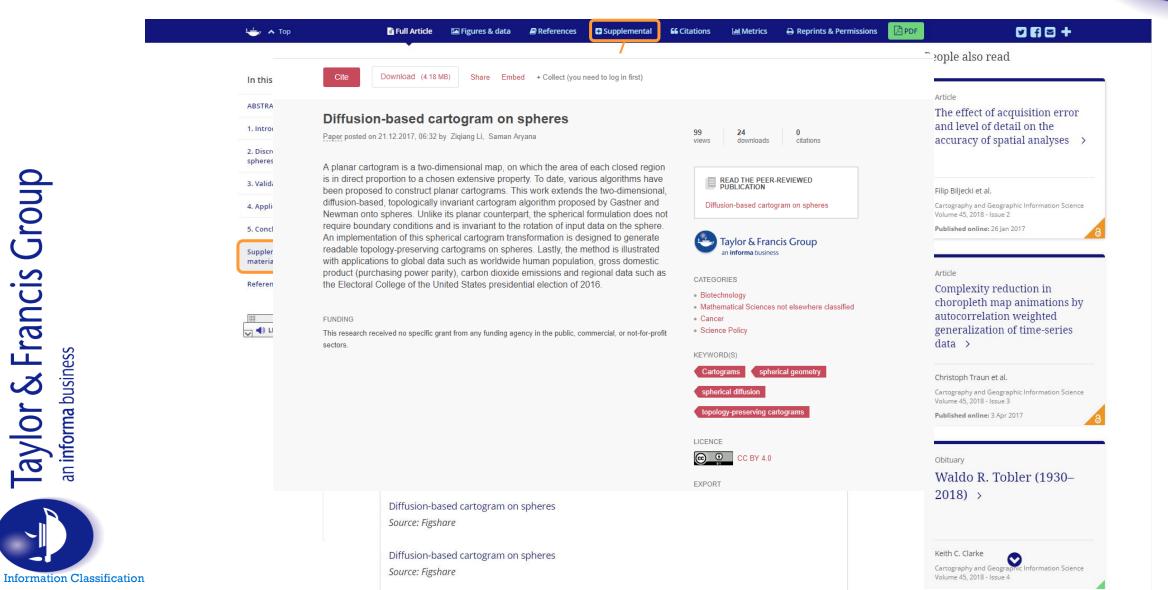


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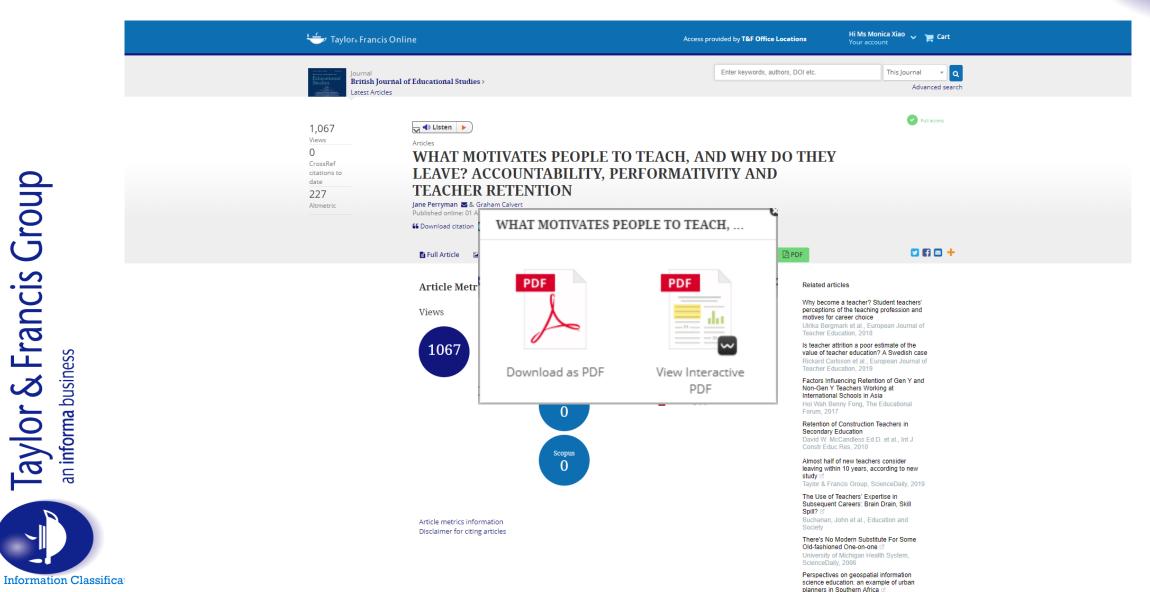
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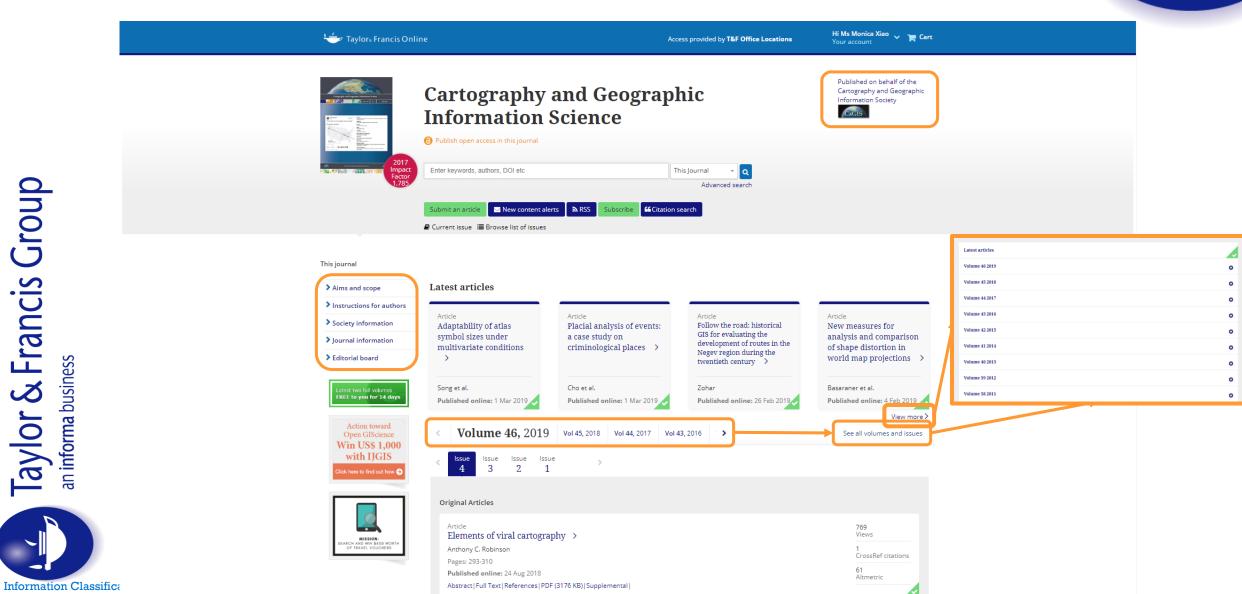
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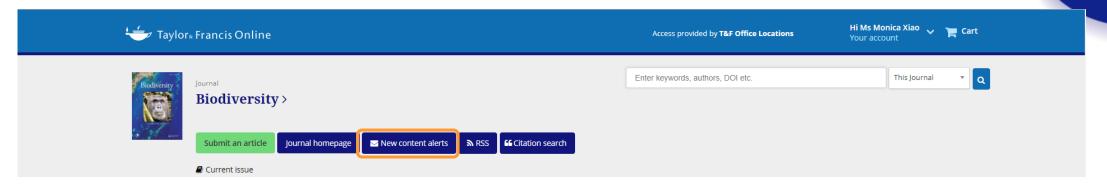




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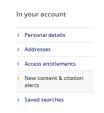
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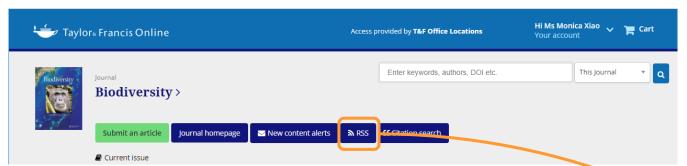
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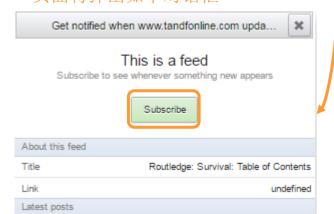
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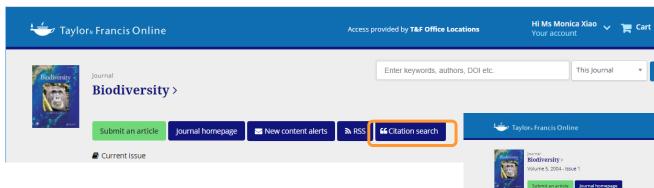


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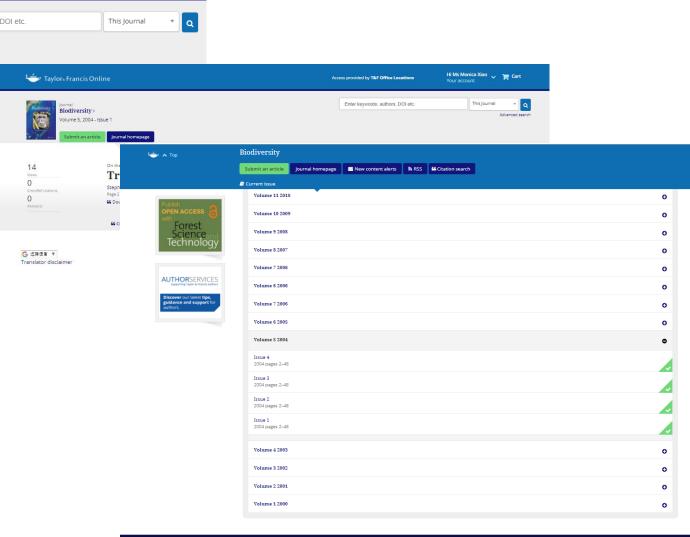




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